Learning a Distance Metric for Structured Network Prediction

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Learning to Compare Examples Workshop, December 8, 2006

Outline

- Introduction
 - Context, motivation & problem definition
- Contributions
 - Structured network characterization
 - Network prediction model
 - Distance-based score function
 - Maximum-margin learning
- Experiments
 - 1-Matchings on toy data
 - Equivalence networks on face images
 - Preliminary results on social networks
- Future & related work, summary and conclusions

Context

- Pattern classification
 - Inputs & outputs
 - Independent and identically distributed
- Pattern classification for structured objects
 - Sets of inputs & outputs
 - Model dependencies amongst output variables
- Parameterize model using a Mahalanobis distance metric

Motivation for structured network prediction

• Man made and natural formed networks exhibit a high degree of structural regularity

Motivation

• Scale free networks



Protein-interaction network, Barabási & Oltvai, Nature Genetics, 2004



Jeffrey Heer, Berkeley

Motivation

• Equivalence networks







Equivalence network on Olivetti face images - union of vertex-disjoint complete subgraphs





Structured network prediction

- Given
 - n entities with attributes $\{\mathbf{x}_1,\ldots,\mathbf{x}_n\}$ $\mathbf{x}_k \in \mathbb{R}^d$
 - And a structural prior on networks
- Output
 - Network of similar entities with desired structure

$$\mathbf{y} = (y_{j,k})$$
$$y_{j,k} \in \{0,1\}$$





(4)

2

3

(1)

5

Applications

Tasks

- Initializing
- Augmenting
- Filtering of networks
- Domains
 - E-commerce
 - Social network analysis
 - Network biology

Challenges for SNP

- How can we take structural prior into account?
 - Complex dependencies amongst atomic edge predictions

- What similarity should we use?
 - Avoid engineering similarity metric for each domain

Structural network priors - 1 • Degree $\delta(v)$ of a node • Number of incident edges •

- Degree distribution
 - Probability of node having degree k, for all k

Degree distributions



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Structural network priors - 2

- Combinatorial families
 - Chains
 - Trees & forests
 - Cycles
 - Unions of disjoint complete subgraphs
 - Generalized matchings



• We consider B-matching networks $\,\mathcal{B}\,$ because they are flexible and efficient

Predictive Model

- Maximum weight b-matching as predictive model
 - 1. Receive nodes and attributes
 - 2. Compute edge weights $\mathbf{s} = (s_{j,k})$ $s_{j,k} \in \mathbb{R}$
 - 3. Select a b-matching with maximal weight

$$\max_{\mathbf{y}\in\mathcal{B}}\sum_{j,k}y_{j,k}s_{j,k}=\max_{\mathbf{y}\in\mathcal{B}}\mathbf{y}^T\mathbf{s}$$





• B-matchings requires $\mathcal{O}(n^3)$ time

Structured network prediction

• The question that remains is how do we compute the weights?

Learning the weights

 Weights are parameterized by a Mahalanobis distance metric

•
$$s_{j,k} = (x_j - x_k)^T Q(x_j - x_k) \qquad Q \succeq 0$$

 In other words, we want to find the best linear transformation (rotation & scaling) to facilitate b-matching

Learning the weights

- We propose to learn the weights from one or more partially observed networks
 - We observe the attributes of all nodes
 - But only a subset of the edges
 - •
- Transductive approach
 - Learn weights to "fit" training edges
 - While structured network prediction is performed over training and test edges



Example

• Given the following nodes & edges







• 1-matching



• 1-matching

Taskar et al. 2005

• We use the dual-extragradient algorithm to learn Q

• Define the margin to be the minimum gap between the predictive values of the true structure $y \in \mathcal{B}$ and each possible alternative structure $y_1, y_2, \ldots \in \mathcal{B}$

$$\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}$$

 \mathbb{R}

$$\mathbf{s}_Q(\mathbf{x}) = \operatorname{vec} egin{bmatrix} d_{1,1} & d_{1,2} \ d_{1,2} \ d_{1,2} \ \end{pmatrix}$$

 $\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}_2$ $\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}_3$

 $\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}_1$

Taskar et al. 2005

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• Define the margin to be the minimum gap between the predictive values of the true structure $y \in \mathcal{B}$ and each possible alternative structure $y_1, y_2, \ldots \in \mathcal{B}$ $\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}$ $\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}$ $\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}_1$ $\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}_1$ $\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}_1$

$$\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}_2 \ \mathbf{s}_Q(\mathbf{x})^T \mathbf{y}_3$$

 \mathbb{R}

 \mathbb{R}

Taskar et al. 2005

• We use the dual-extragradient algorithm to learn Q

Define the margin to be the minimum gap between the predictive values of the true structure $y \in \mathcal{B}$ and each possible alternative structure $y_1, y_2, \ldots \in \mathcal{B}$ $\mathbf{s}_{Q}(\mathbf{x})^{T}\mathbf{y} \qquad \qquad \mathbf{s}_{Q}(\mathbf{x}) = \operatorname{vec} \begin{bmatrix} d_{1,1} \ d_{1,2} \\ d_{1,2} \\ \mathbf{s}_{Q}(\mathbf{x})^{T}\mathbf{y}_{1} \\ \mathbf{s}_{Q}(\mathbf{x})^{T}(\mathbf{y} - \mathbf{y}_{1}) \geq 1 \\ \mathbf{s}_{Q}(\mathbf{x})^{T}(\mathbf{y} - \mathbf{y}_{2}) \geq 1 \\ \mathbf{s}_{Q}(\mathbf{y} - \mathbf{y}_{2}) \geq 1 \\ \mathbf{s}_{Q}(\mathbf{y} - \mathbf{y}_{2}) \leq 1$ $\mathbf{s}_Q(\mathbf{x})^T \mathbf{y}_2 \ \mathbf{s}_Q(\mathbf{x})^T \mathbf{y}_3$

- You can think of the dual extragradient algorithm as successively minimizing the violation of the gap constraints
- Each iteration focusses on "worst offending network"

1.
$$\mathbf{y}_{\text{bad}} = \operatorname*{argmin}_{\tilde{\mathbf{y}} \in \mathcal{B}} \mathbf{s}_Q(\mathbf{x})^T \tilde{\mathbf{y}}$$

- You can think of the dual extragradient algorithm as successively minimizing the violation of the gap constraints
- Each iteration focusses on "worst offending network"

1.
$$\mathbf{y}_{\text{bad}} = \operatorname*{argmin}_{\tilde{\mathbf{y}} \in \mathcal{B}} \mathbf{s}_Q(\mathbf{x})^T \tilde{\mathbf{y}}$$

2.
$$Q = Q - \epsilon \frac{\partial \text{gap}(\mathbf{y}, \mathbf{y}_{\text{bad}})}{\partial Q}$$

- You can think of the dual extragradient algorithm as successively minimizing the violation of the gap constraints
- Each iteration focusses on "worst offending network"

1.
$$\mathbf{y}_{\text{bad}} = \operatorname*{argmin}_{\tilde{\mathbf{y}} \in \mathcal{B}} \mathbf{s}_Q(\mathbf{x})^T \tilde{\mathbf{y}}$$

2. $Q = Q - \epsilon \frac{\partial \operatorname{gap}(\mathbf{y}, \mathbf{y}_{\text{bad}})}{\partial Q}$

$$d_{j,k} = (x_j - x_k)^T Q(x_j - x_k) = \langle Q, (x_j - x_k)(x_j - x_k)^T \rangle$$
linear in Q
$$\left(\sum_{jk \in \mathrm{FP}} (x_j - x_k)(x_j - x_k)^T - \sum_{jk \in \mathrm{FN}} (x_j - x_k)(x_j - x_k)^T\right)$$

- You can think of the dual extragradient algorithm as successively minimizing the violation of the gap constraints
- Each iteration focusses on "worst offending network"



• How does it work in practice?

Error metrics for SNP

- Recall & hamming loss (#FP + #FN)
 - Reward the correct structure, but not the distance metric
- We construct a structure-sensitive ROC curve
 - Structure predictions are blended with distances

$$\tilde{y}_{j,k} = y_{j,k} + \epsilon \exp(-d_{j,k})$$



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300 nodes in 20 1-matching structure X,Y features

Example



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Equivalence networks

• Olivetti face images











300 images 10 per person 30 PCA features

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Reconstructions of rows of sqrt(Q)



Reconstructions of rows of sqrt(Q) using scaled rows (x8)



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Reconstructions of rows of sqrt(Q) using scaled rows (x1 1)



Reconstructions of rows of sqrt(Q) using scaled rows (x14)



Social network ... and future work



6848 users "assume" b-matching structure bag-of-words features (favorite music, books, etc.)



Jeffrey Heer, Berkeley

Social network ... and future work



Future work

- Selecting the parameter b
- Learning and matching to the true degree distribution
- Learning over alternate combinatorial structures such as trees, forests, cliques

Related Work

• Structured output models

- B. Taskar, S. Lacoste-Julien, and M. I. Jordan "Structured prediction, dual extragradient and bregman projections" NIPS 2005
- I. Tsochantaridis and T. Joachims and T. Hofmann and Y. Altun "Large Margin Methods for Structured and Interdependent Output Variables" JMLR
- F. Sha, L. Saul "Large Margin Gaussian Mixture Models for Automatic Speech Recognition" NIPS 2006
- Network reconstruction
 - A. Culotta, R. Bekkerman, and A. McCallum "Extracting social networks and contact information from email and the web" AAAI 2004
 - M. Rabbat, M. Figueiredo, and R. Nowak. "Network inference from cooccurrences" University of Wisconsin 2006
- Network simulation
 - R. Albert and A. L. Barabasi "Statistical mechanics of complex networks", Reviews of Modern Physics, and many others ...

Related Work

- Distance metric learning
 - J. Goldberger, S. Roweis, G. Hinton, and R. Salakhutdinov "Neighbourhood components analysis", NIPS 2004
 - E. Xing, A. Ng, M. Jordan, and S. Russell "Distance metric learning, with application to clustering with side-information" NIPS 2003
 - S. Shalev-Shwartz, Y. Singer, and A. Ng "Online and batch learning of pseudometrics" ICML 2004, and many others ...

Conclusions

- We address a novel structured network prediction problem
- We developed a structured output model that uses a structural network priors to make predictions
- We parameterized the model using a Mahalanobis distance metric
- We demonstrated that it is possible to learn a distance suitable for structured network prediction
- The advantage of using a structured output model to predict edges is that we obtain a higher recall for comparable precision / FP rates

Thank you for your attention Question & comments?